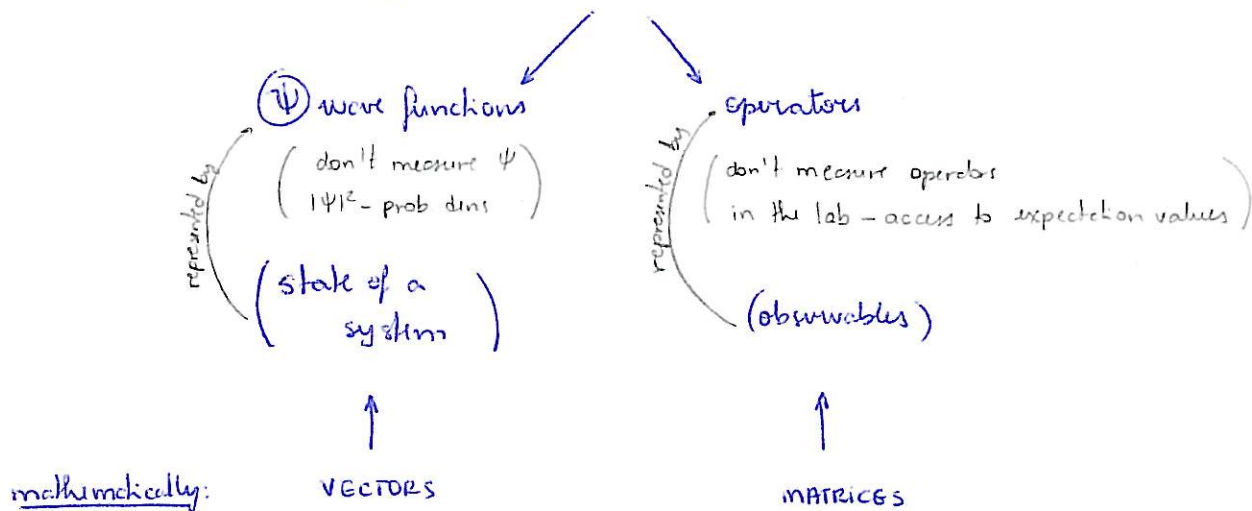


Formalism

Formalism of QM is based on



Operators act on the vectors as linear transformations

language of QM is linear algebra

VECTORS

a) real space: $\vec{r} = 2\hat{i} + 3\hat{j}$, where \hat{i} and $\hat{j} \rightarrow$ ORTHONORMAL BASIS

using the notation $\hat{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\hat{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

\rightarrow components are real numbers

$$\vec{r} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

\rightarrow up to 3D

VECTORS
in QM

→ complex numbers
→ no restriction for dimensions

$$\Psi = |\alpha\rangle$$

↳ ket (Dirac notation)

$$|\alpha\rangle = \begin{pmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ \vdots \end{pmatrix}$$

d_1, d_2, d_3, \dots components of $|\alpha\rangle$ in a certain
ORTHONORMAL basis

Example

$$\begin{matrix} \text{LULUL} \\ 1000 \rightarrow |\phi_1\rangle \\ 0100 \rightarrow |\phi_2\rangle \\ 0010 \rightarrow |\phi_3\rangle \\ 0001 \rightarrow |\phi_4\rangle \end{matrix} \left\{ \begin{array}{l} |\alpha\rangle = d_1|\phi_1\rangle + d_2|\phi_2\rangle + d_3|\phi_3\rangle + d_4|\phi_4\rangle \\ \text{orthonormal } \underbrace{(1000)}_{\phi_1} \cdot \underbrace{\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}}_{\phi_2} = 0 \end{array} \right.$$

$$|\phi_1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ etc} \quad |\alpha\rangle = \begin{pmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \end{pmatrix}$$

→ Vector space set of vectors with a set of scalars which is
CLOSED [= operations are well defined, don't carry you out of
the vector space]

under two operations:

o) vector addition $|\alpha\rangle + |\beta\rangle = |\gamma\rangle$

commutative

$$|\alpha\rangle + |\beta\rangle = |\beta\rangle + |\alpha\rangle$$

associative

$$|\alpha\rangle + (|\beta\rangle + |\gamma\rangle) = (|\alpha\rangle + |\beta\rangle) + |\gamma\rangle$$

zero vector $|\alpha\rangle + |0\rangle = |\alpha\rangle$

inverse vector $-\alpha \Rightarrow |\alpha\rangle + (-|\alpha\rangle) = |0\rangle$

o) scalar multiplication $a|\alpha\rangle = |\gamma\rangle$

distributive, associative

→) linear combinations

$$a|\alpha\rangle + b|\beta\rangle + c|\gamma\rangle + \dots = |\Omega\rangle$$

$$\Psi(x) = \sum c_n \Psi_n(x)$$

→) linearly independent

$|\lambda\rangle$ is L.I. of $|\alpha\rangle, |\beta\rangle, |\gamma\rangle$ if it cannot be written as a linear comb. of them

Ex: k is L.I. of i and j } any vector in xy plane is L. dependent on i and j

→) SPAN

a set of vectors is said to SPAN the space if every vector can be written as a linear combination of this set } set also called COMPLETE

Ex: in 2D i and j SPAN the space

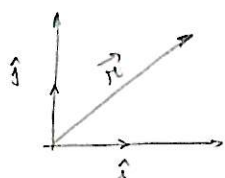
→) BASIS

a set of L.I. vectors that SPAN the space

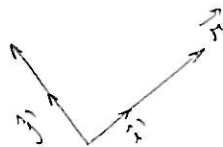
the number of vectors in any basis is the DIMENSION of the space

→) COMPONENTS

in a certain basis, any vector is uniquely represented by its components

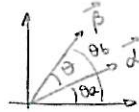


$$\vec{r} = 2\hat{i} + 3\hat{j}$$



$$\vec{r} = \sqrt{13} \hat{i}'$$

the vector is always the same but its components change according to the basis

→ Inner product(dot product: $\vec{a} \cdot \vec{\beta} = d \beta \cos \theta$)decomposed in an orthonormal basis \hat{i}, \hat{j} $\left\{ \begin{array}{l} \hat{i} \cdot \hat{j} = 0 \\ \|\hat{i}\| = 1 \\ \|\hat{j}\| = 1 \end{array} \right.$

$$\vec{a} \cdot \vec{\beta} = d \beta \cos \theta = d \beta \cos(\theta_b - \theta_a) = d \beta (\cos \theta_b \cos \theta_a + \sin \theta_b \sin \theta_a)$$

$$= d \beta \left(\frac{b_x a_x}{d \beta} + \frac{b_y a_y}{d \beta} \right) = a_x b_x + a_y b_y$$

$$\vec{a} \cdot \vec{\beta} = \underbrace{(a_x \ a_y)}_{\text{row vector } \langle a |} \underbrace{\begin{pmatrix} b_x \\ b_y \end{pmatrix}}_{\text{column vector } | \beta \rangle} = \langle a | \beta \rangle = a_x b_x + a_y b_y$$

 $\langle a | \beta \rangle$

$$| \beta \rangle = \underbrace{(b_1 | e_1 \rangle + b_2 | e_2 \rangle + b_3 | e_3 \rangle + \dots)}_{\text{BASIS}}$$

$$| a \rangle = a_1 | e_1 \rangle + a_2 | e_2 \rangle + a_3 | e_3 \rangle + \dots$$

$$\Rightarrow \underbrace{\langle a |}_{\text{bra}} = \langle e_1 | a_1^\vee + \langle e_2 | a_2^\vee + \langle e_3 | a_3^\vee + \dots$$

$$\langle a | \beta \rangle = a_1^\vee b_1 \langle e_1 | e_1 \rangle + a_2^\vee b_2 \langle e_1 | e_2 \rangle + a_3^\vee b_3 \langle e_1 | e_3 \rangle + \dots$$

BUT, if the basis is ORTHONORMAL $\leftarrow \langle e_i | e_j \rangle = \delta_{ij}$

then

$$\langle a | \beta \rangle = a_1^\vee b_1 + a_2^\vee b_2 + a_3^\vee b_3 + \dots$$

← very convenient

$$\hookrightarrow \underbrace{(a_1^\vee \ a_2^\vee \ a_3^\vee \ \dots)}_{\text{(row vector)}} \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \underbrace{(\text{column vector})}_{\text{because basis is orthonormal}}$$

most of the vectors we encounter in QM are functions
and they live in

infinite-dimensional spaces

The collection of all functions of x constitutes a vector space

But to represent a possible physical state it must be normalized

$$\int |\psi|^2 dx = 1$$

→ The set of all square-integrable functions on an interval

$$f(x) \text{ such that } \int_a^b |f(x)|^2 dx < \infty$$

constitutes a vector space called

HILBERT SPACE

In a infinite dim space, we define the inner-product as

$$\langle f | g \rangle \equiv \int_a^b f(x)^* g(x) dx$$

Properties:

$$\bullet \langle g | f \rangle = \langle f | g \rangle^*$$

$$\bullet \langle f | f \rangle \geq 0$$

$$\bullet \text{ NORM: } \|f\| \equiv \sqrt{\langle f | f \rangle}$$

$$\bullet \text{ If } \|f\| = 1 \rightarrow \text{vector/function is normalized}$$

$$\text{Ex: } \|a\| = \sqrt{\langle a | a \rangle} = 1 \Rightarrow |a_1|^2 + |a_2|^2 + |a_3|^2 + \dots = 1$$

$$\bullet \langle f | g \rangle = 0 \equiv \text{orthogonal}; \quad \langle f_n | f_m \rangle = \delta_{mn} \leftarrow \text{orthonormal}$$

• set is complete if any function (in Hilbert space) can be expressed as linear comb

$$f(x) = \sum_{n=1}^{\infty} c_n f_n(x) \quad (\text{orthonorm.}) \quad \boxed{c_n = \langle f_n | f \rangle}$$

MATRICES \rightarrow operators

multiply vectors by a scalar
rotate vectors

linear transformations (\hat{T})

$$\hat{T}|d\rangle = |d'\rangle$$

1) transpose \tilde{T}

symmetric: $T = \tilde{T}$ antisym: $\tilde{T} = -T$

2) complex conjugate T^*

real: $T^* = T$ imagin: $T^* = -T$

\Rightarrow hermitian conjugate (or ADJOINT)

$$T^\dagger = \tilde{T}^*$$

~~operator matrix is hermitian (or self-adjoint)~~
~~if $T^\dagger = T$~~
 ~~$T^\dagger = T$~~

$$(|\alpha\rangle)^\dagger = \langle\alpha|$$

bra is the hermitian conjugate of the ket (and vice-versa)

OBSERVABLE are represented by hermitian operators

$$\left\{ \begin{array}{l} |\nu\rangle = T|\mu\rangle \\ \langle w|\nu\rangle = \langle w|T|\mu\rangle \\ \langle w|\nu\rangle^* = \langle\nu|w\rangle = \langle\mu|T^\dagger|w\rangle \\ \langle w| = \langle\mu|T^\dagger \end{array} \right.$$

Expectation value of an OBSERVABLE

$$\langle T \rangle = \int \psi^* \hat{T} \psi dx = \langle \psi | T | \psi \rangle$$

$$\langle T \rangle = \langle \psi | T | \psi \rangle$$

$$\langle \psi | T | \psi \rangle$$

$$\langle \psi | T | \psi \rangle^* = \langle T | \psi | \psi \rangle = \langle \psi | T^\dagger | \psi \rangle$$

$$\langle T \rangle^* = (\langle \psi | T | \psi \rangle)^* = \langle \psi | T^\dagger | \psi \rangle$$

(see next page)

since the outcome of a measurement has to be real

↓

$$\langle T \rangle = \langle T \rangle^*$$

↓

$$T = T^\dagger$$

a square matrix \hat{T} is hermitian (or self-adjoint)

if it is equal to T^\dagger

OBSERVABLES are represented by hermitian operators

Is momentum a hermitian operator?

$$\langle p \rangle = \langle \psi | p | \psi \rangle = \int \psi^* \frac{\hbar}{i} \frac{d\psi}{dx} dx$$

$$\langle p \rangle^* = \langle \psi | p | \psi \rangle^* = \int \left(\psi^* \frac{\hbar}{i} \frac{d\psi}{dx} \right)^* dx = \int \psi \left(-\frac{\hbar}{i} \frac{d\psi^*}{dx} \right) dx$$

$$\text{by parts } -\frac{\hbar}{i} \psi \psi^* \Big|_{-\infty}^{\infty} + \frac{\hbar}{i} \int \frac{d\psi}{dx} \psi^* dx = \int \psi^* \frac{\hbar}{i} \frac{d\psi}{dx} dx$$

$$\text{so } \langle p \rangle - \langle p \rangle^* = \int \frac{\hbar}{i} \frac{d}{dx} (\psi^* \psi) dx = \frac{\hbar}{i} \psi^* \psi \Big|_{-\infty}^{\infty} = 0,$$

$$\Rightarrow \langle p \rangle = \langle p \rangle^* \Rightarrow \boxed{\hat{p} = \hat{p}^\dagger}$$

more generally, a hermitian operator satisfies

$$\langle \Psi_1 | T \Psi_2 \rangle = \langle T \Psi_1 | \Psi_2 \rangle$$

which is equivalent to

$$T = T^\dagger$$

because

$$\langle T \Psi_1 | \Psi_2 \rangle = \langle \Psi_1 | T^\dagger | \Psi_2 \rangle$$

Showing that

$$\langle T \Psi_1 | \Psi_2 \rangle = \langle \Psi_1 | T^\dagger | \Psi_2 \rangle$$

with matrices

$$|T \Psi_1\rangle = \begin{pmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} t_{11} a_1 + t_{12} a_2 \\ t_{21} a_1 + t_{22} a_2 \end{pmatrix} \Rightarrow \langle T \Psi_1 | = (|T \Psi_1\rangle)^\dagger = \begin{pmatrix} t_{11}^* a_1^* + t_{12}^* a_2^* & t_{21}^* a_1^* + t_{22}^* a_2^* \end{pmatrix}$$

$$\langle \Psi_1 | T^\dagger = (a_1^* \ a_2^*) \begin{pmatrix} t_{11}^* & t_{21}^* \\ t_{12}^* & t_{22}^* \end{pmatrix} = (a_1^* t_{11}^* + a_2^* t_{12}^* \quad a_1^* t_{21}^* + a_2^* t_{22}^*)$$

$$\langle T \Psi_1 | = \langle \Psi_1 | T^\dagger$$

Showing that momentum is a hermitian operator

$$\langle f | p g \rangle = \int f^* \frac{\hbar}{i} \frac{dg}{dx} dx = \frac{\hbar}{i} f^* g \Big|_{-\infty}^{\infty} - \frac{\hbar}{i} \int \frac{df^*}{dx} g dx = \int \left(\frac{\hbar}{i} \frac{df^*}{dx} \right) g dx$$

$$\langle p f | g \rangle$$

•) matrix multiplication is not, in general, commutative

$$\text{commutator: } [S, T] = ST - TS$$

•) transpose of product is transpose of each in reverse order

$$(\widetilde{ST}) = \widetilde{T} \widetilde{S}$$

$$(\widetilde{ST})_{ki} = (ST)_{ik} = \sum_j S_{ij} T_{jk} = \sum_j T_{jk} S_{ij} = \sum_j (\widetilde{T})_{kj} (\widetilde{S})_{ji} = (\widetilde{T} \widetilde{S})_{ki}$$

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad \widetilde{A} = \begin{pmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{pmatrix}$$

$$A_{12} = \widetilde{A}_{21}$$

$$\downarrow \quad \downarrow$$

$$a_{12} = a_{12}$$

$$\Rightarrow (\widetilde{ST}) = \widetilde{T} \widetilde{S}$$

•) hermitian conjugate

$$(ST)^\dagger = T^\dagger S^\dagger$$

$$(ST)^\dagger = (\widetilde{ST})^* = (\widetilde{T} \widetilde{S})^* = T^\dagger S^\dagger$$

•) unit matrix

$$I = \begin{pmatrix} 1 & & & 0 \\ & \ddots & & \\ & & 1 & \\ 0 & & & \ddots \end{pmatrix}$$

inverse of a square matrix

$$T^{-1} T = T T^{-1} = \mathbb{1}$$

$$T^{-1} = \frac{1}{\det T} \tilde{C}$$

transpose
matrix of cofactors

$$C_{11} = d(-1)^2 \quad C_{12} = c(-1)^3 \Rightarrow \tilde{C} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$C_{21} = b(-1)^3 \quad C_{22} = a(-1)^4$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow \det A = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = \underline{ad - bc}$$

$$A^{-1} = \frac{1}{(ad-bc)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \Rightarrow \det A = \underbrace{a \begin{vmatrix} e & f \\ h & i \end{vmatrix}}_{C_{11}} - \underbrace{b \begin{vmatrix} d & f \\ g & i \end{vmatrix}}_{C_{12}} + \underbrace{c \begin{vmatrix} d & e \\ g & h \end{vmatrix}}_{C_{13}}$$

$$a(-1)^{1+1} \quad b(-1)^{1+2} \quad c(-1)^{1+3}$$

cofactors for one row or one column

cofactor $C_{ij} = (-1)^{i+j} |M_{ij}|$

$(n-1) \times (n-1)$ matrix that results from deleting i -th row and j -th column of original matrix

\Rightarrow unitary matrix

$$U^\dagger = U^{-1}$$

evolution operator of a CLOSED system is unitary